4 Legged robots and sources:

[Frontiers | Oncilla Robot: A Versatile Open-Source Quadruped Research Robot With Compliant Pantograph Legs | Robotics and AI (frontiersin.org)](https://www.frontiersin.org/articles/10.3389/frobt.2018.00067/full#h2)

[Maera: A Hybrid Wheeled-Legged Robot Designed for Research and Education | SpringerLink](https://link.springer.com/chapter/10.1007/978-3-030-67411-3_22)

[Open Dynamic Robot Initiative (open-dynamic-robot-initiative.github.io)](https://open-dynamic-robot-initiative.github.io/)

[Open Dynamic Robot Initiative (github.com)](https://github.com/open-dynamic-robot-initiative)